

# HRSC & other datasets

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# HRSC & other datasets

- Integrating HRSC with other datasets (e.g. MOC, THEMIS, etc.)
- primary source of information and support:

<http://isis.astrogeology.usgs.gov/>

<http://isis.astrogeology.usgs.gov/IsisSupport/>

# ISIS 2

## Tutorials:

<http://isis.astrogeology.usgs.gov/documents/Isis2Tutorials/index.html>

- MOC processing

[http://isis.astrogeology.usgs.gov/Isis2/isis-bin/mgs\\_moc\\_processing.cgi](http://isis.astrogeology.usgs.gov/Isis2/isis-bin/mgs_moc_processing.cgi)

- THEMIS processing

[http://isis.astrogeology.usgs.gov/Isis2/isis-bin/themis\\_processing.cgi](http://isis.astrogeology.usgs.gov/Isis2/isis-bin/themis_processing.cgi)

# ISIS 3 ...

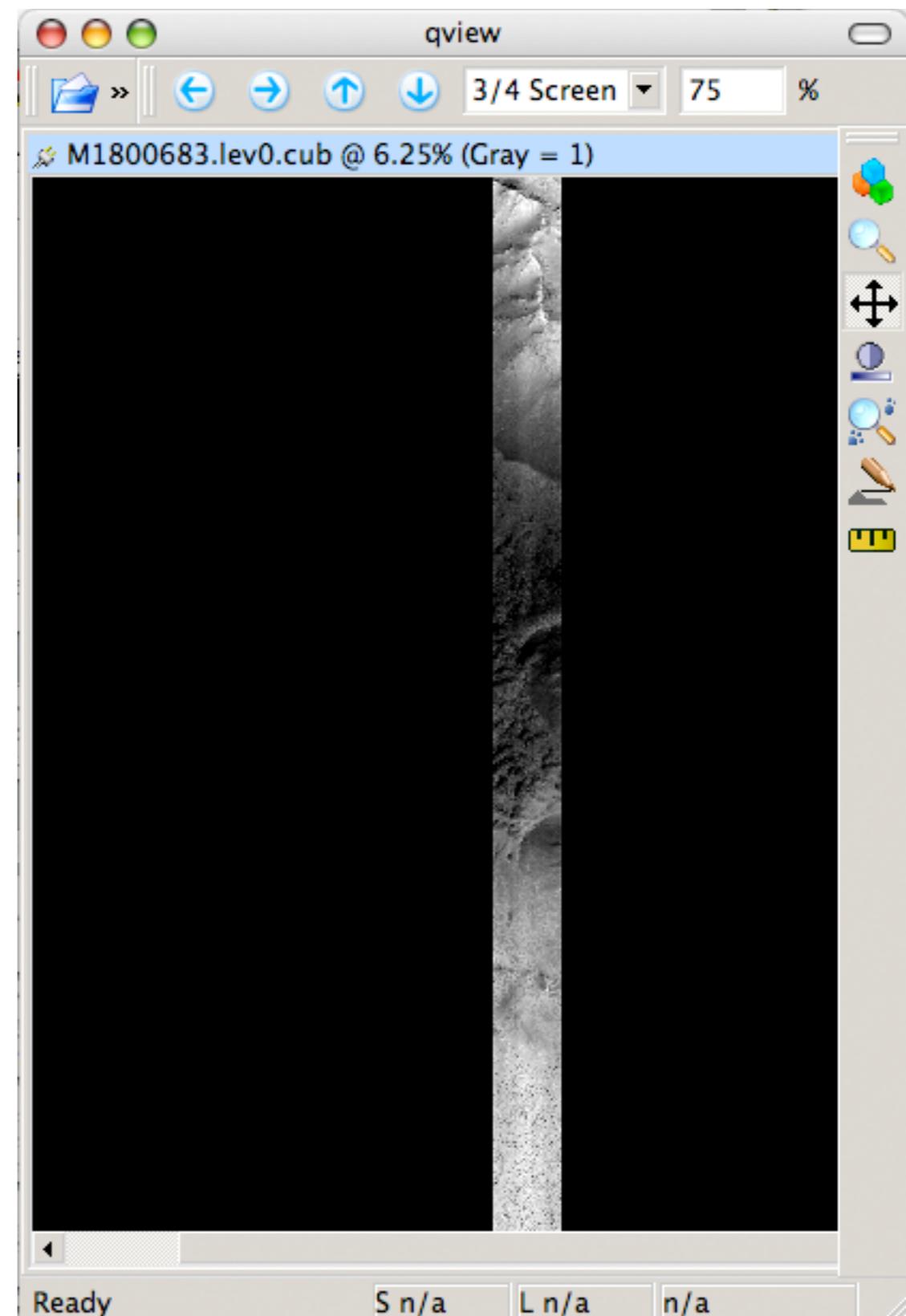
e.g. MOC

<http://isis.astrogeology.usgs.gov/IsisWorkshop/Lessons/WorkingWithMOC/>

e.g. HiRISE

<http://isis.astrogeology.usgs.gov/IsisWorkshop/Lessons/WorkingWithHiRISE/>

# MOC on ISIS 3



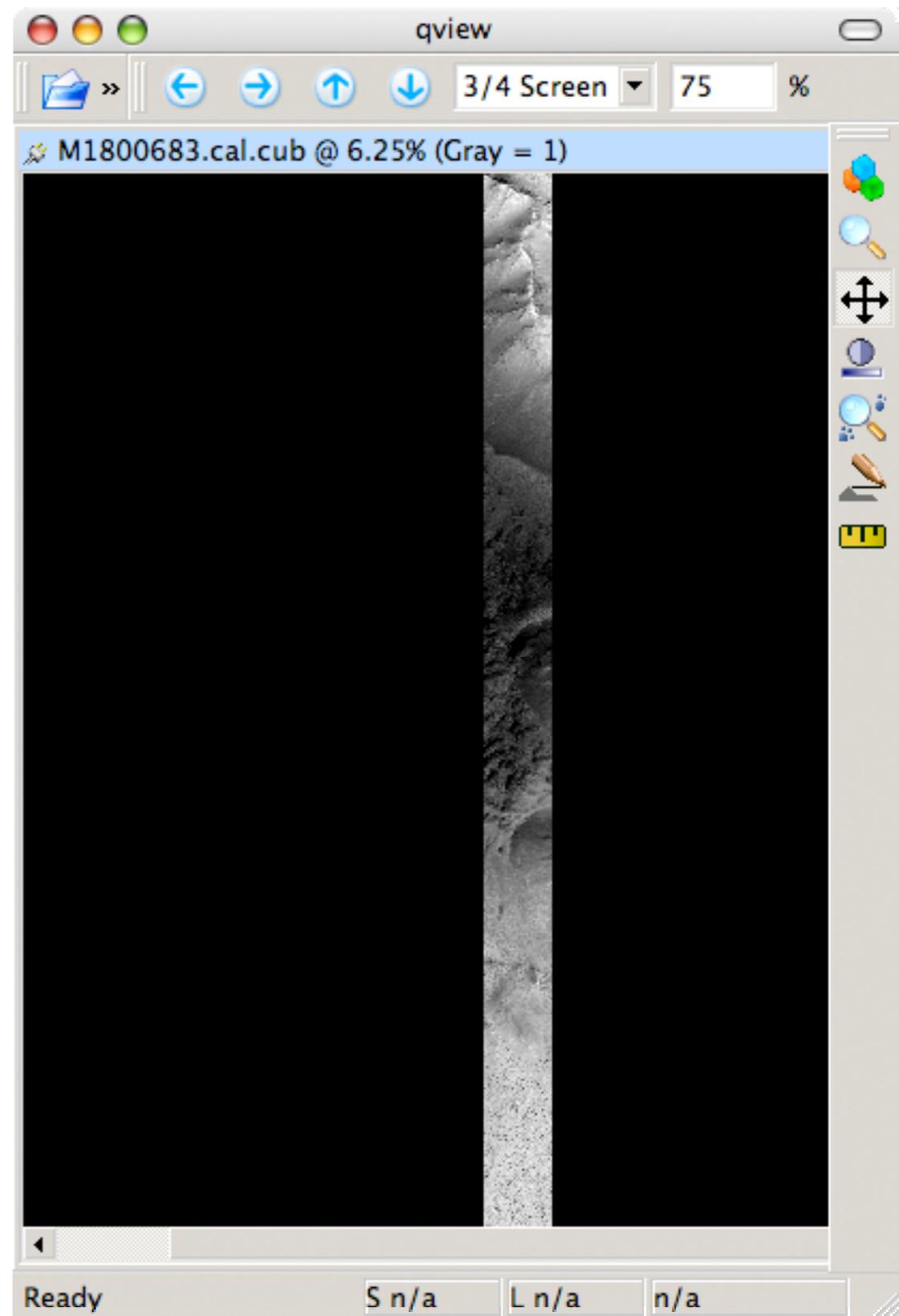
```
moc2isis from=M1800683.img to=M1800683.lev0.cub
```

```
spiceinit from=M1800683.lev0.cub
```

```
moccal from=M1800683.lev0.cub to=M1800683.cal.cub
```

```
cam2map
```

# MOC on ISIS 3



```
moc2isis from=M1800683.img to=M1800683.lev0.cub  
spiceinit from=M1800683.lev0.cub  
moccal from=M1800683.lev0.cub to=M1800683.cal.cub  
cam2map
```

# MOC on ISIS 3

```
Group = Mapping  
ProjectionName = Sinusoidal  
CenterLongitude = XX.X  
End_Group
```



```
moc2isis from=M1800683.img to=M1800683.lev0.cub  
spiceinit from=M1800683.lev0.cub  
moccal from=M1800683.lev0.cub to=M1800683.cal.cub  
cam2map
```

Files

FROM /Volumes/Bull/TEST\_HRSC\_ISIS/MOC/M1800683.cal.cub

MAP /usr/local/usgs/isis3/data/base/templates/maps/sinusoidal.map

TO /Volumes/Bull/TEST\_HRSC\_ISIS/MOC/M1800683.lev2.cub

Output Map Resolution

PIXRES

- Compute resolution from input cube (CAMERA)
- Read resolution from input map file (MAP)
- Get resolution from user in meters per pixel (MPP)
- Get resolution from user in pixels per degree (PPD)

RESOLUTION

Output Map Ground Range

DEFALTRANGE

- Compute default range from input cube (CAMERA)
- Read default range from map file (MAP)

SLAT Use default range

ELAT Use default range

SLON Use default range

ELON Use default range

TRIM  Trim pixels outside ground range

# MOC on ISIS 3

```
Group = Mapping
  ProjectionName      = Sinusoidal
  CenterLongitude    = 285.0
  TargetName         = Mars
  EquatorialRadius   = 3396190.0 <meters>
  PolarRadius        = 3376200.0 <meters>
  LatitudeType       = Planetocentric
  LongitudeDirection = PositiveEast
  LongitudeDomain    = 360
  MinimumLatitude    = -5.3663937499135
  MaximumLatitude    = -4.5709158171327
  MinimumLongitude   = 287.99662671879
  MaximumLongitude   = 288.15057299966
  UpperLeftCornerX   = 176845.47445803 <meters>
  UpperLeftCornerY   = -270938.46964656 <meters>
PixelResolution
Scale
  TrueScaleLatitude  = 0.0
End_Group
```

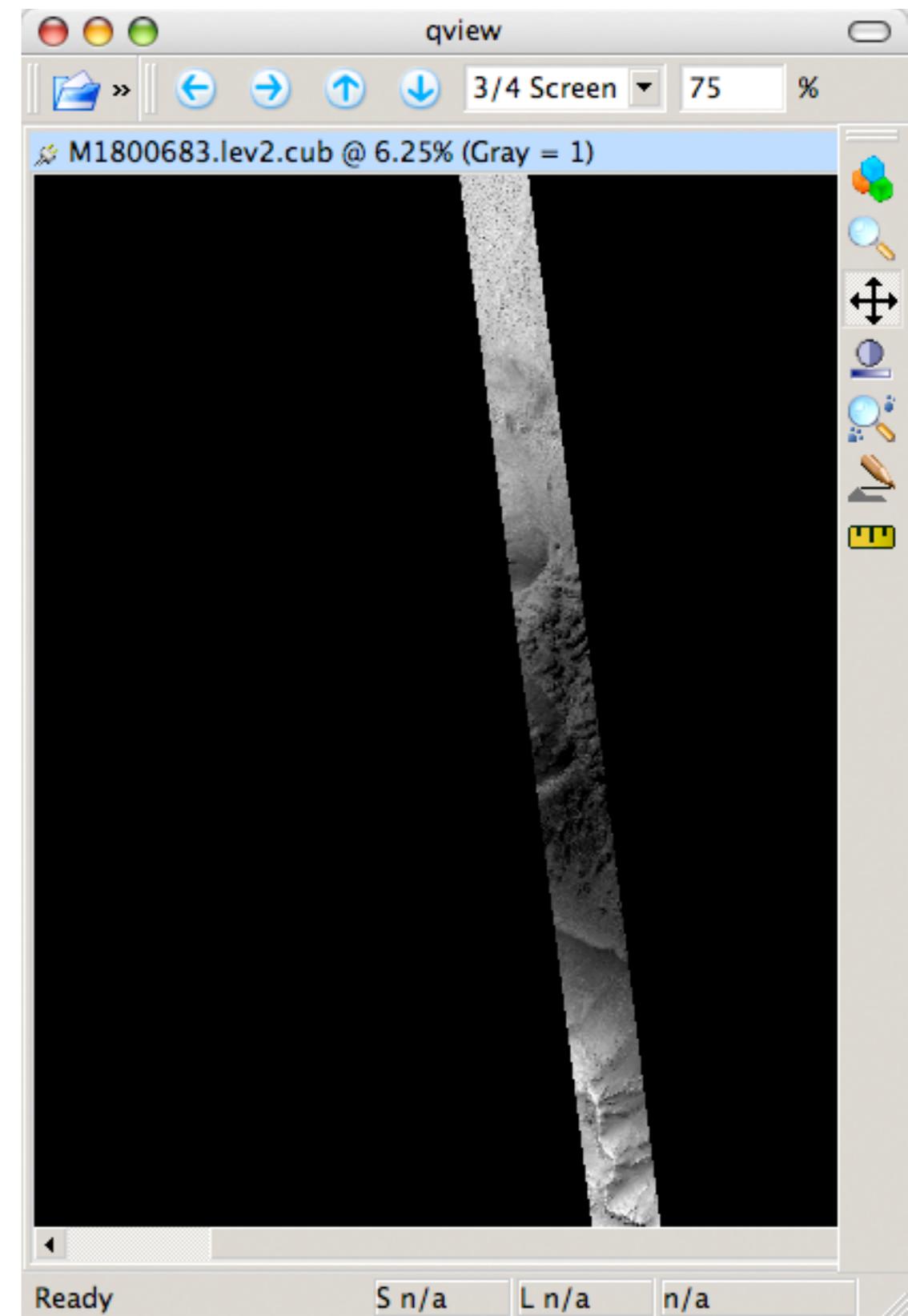
Terminology difference with PDS/VICAR keywords!!!!

moc2isis from=M1800683.img to=M1800683.lev0.cub

spiceinit from=M1800683.lev0.cub

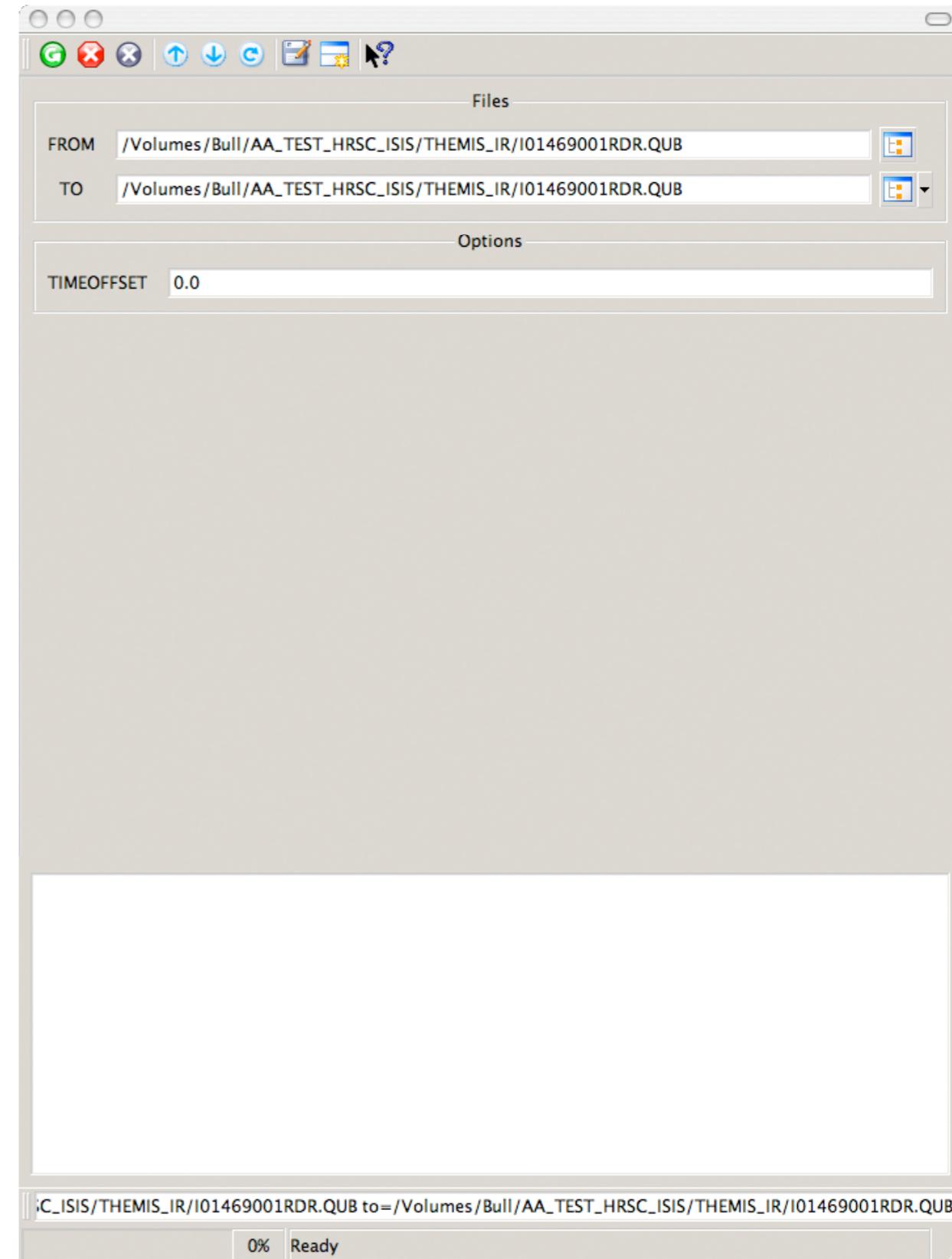
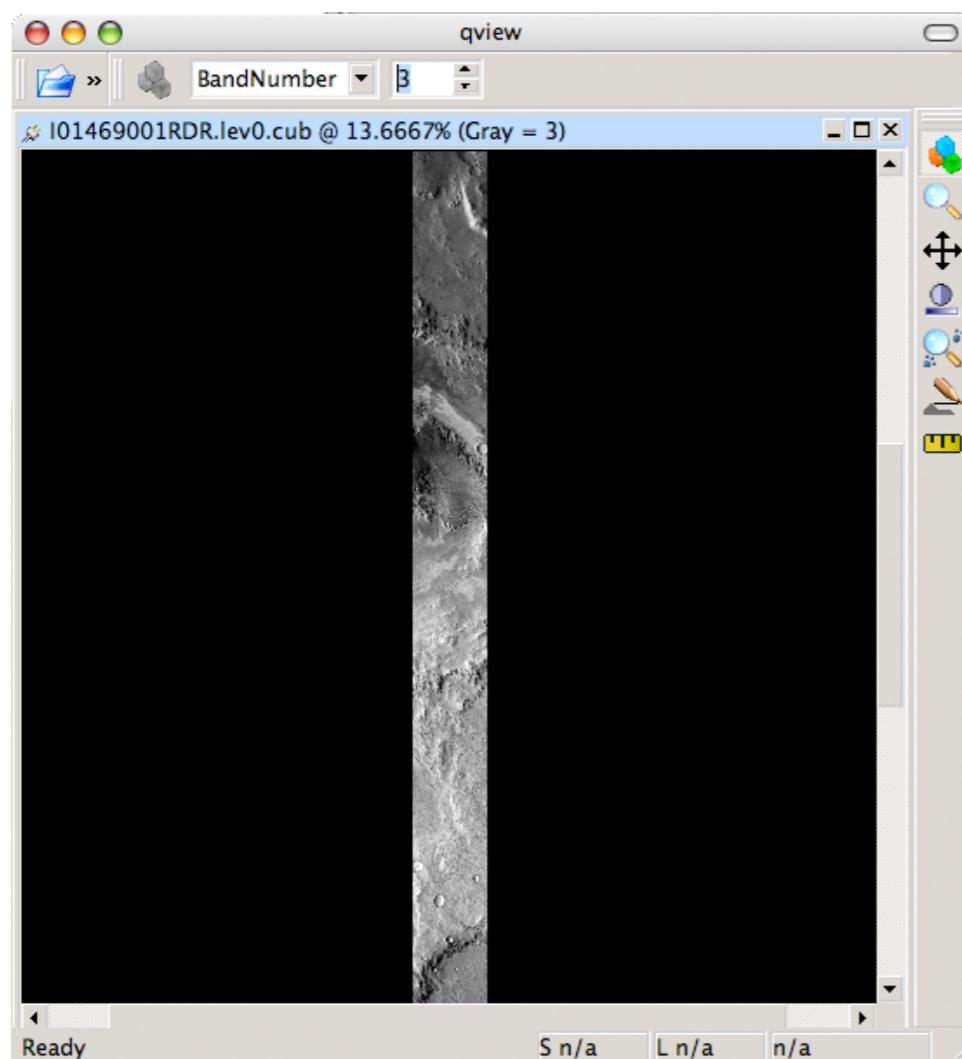
moccal from=M1800683.lev0.cub to=M1800683.cal.cub

cam2map



# THEMIS IR on ISIS 3

“thm2isis”



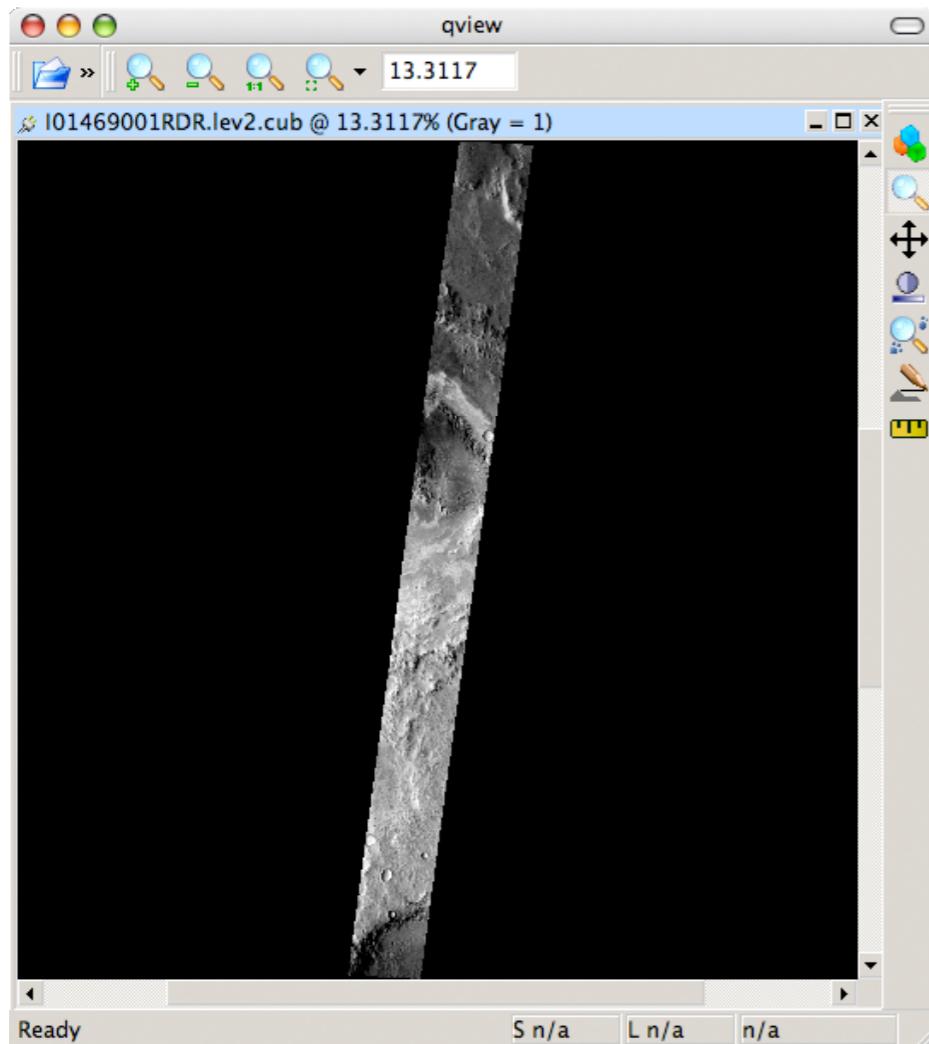
+ further steps...

# THEMIS IR on ISIS 3

OR:

“thmproc”

which includes all basic  
processing steps



The screenshot shows the ISIS 3 processing window for "thmproc". The window is divided into several sections:

- Files:** FROM: /Volumes/Bull/AA\_TEST\_HRSC\_ISIS/THEMIS\_IR/I01469001RDR.QUB; TO: Automatic; BANDS: All; REMOVE:  Remove Intermediate Files.
- Level Processing:** Ingestion:  Import and initialize a Themis RDR file. Mapping:  Process the input file through the map projection phase.
- Ingestion Parameters:** PCK: none; CK: none; SPK: none; Ellipsoid: Use triaxial ellipsoid from PCK (ELLIPSOID) (radio button selected); Shape Model: Search system for a default shape model (SYSTEM) (radio button selected); User specified shape model file (USER): none; MODEL: none.
- Mapping parameters:** MAP: Sinusoidal. A detailed configuration block for the Sinusoidal projection is shown:

```
Group = mapping
ProjectionName      = Sinusoidal
TargetName          = MARS
EquatorialRadius   = 3396190.0 <meters>
PolarRadius         = 3376200.0 <meters>
LatitudeType        = Planetocentric
LongitudeDirection = PositiveEast
LongitudeDomain    = 360
MinimumLatitude    = -8.9908008904776
MaximumLatitude    = -2.8983177421118
MinimumLongitude   = 137.50912762289
MaximumLongitude   = 138.89471256787
PixelResolution     = 97.764274422437 <meters/pixel>
CenterLongitude    = 138.20192009538
Scale               = 606.30222924973 <pixels/degree>
TrueScaleLatitude  = 0.0
UpperLeftCornerX   = -40669.938159734 <meters>
UpperLeftCornerY   = -171674.0658858 <meters>
End_Group
End
```
- thmproc:** Progress bar at 70% completion, status: cam2map: Working.

# HRSC in ISIS3

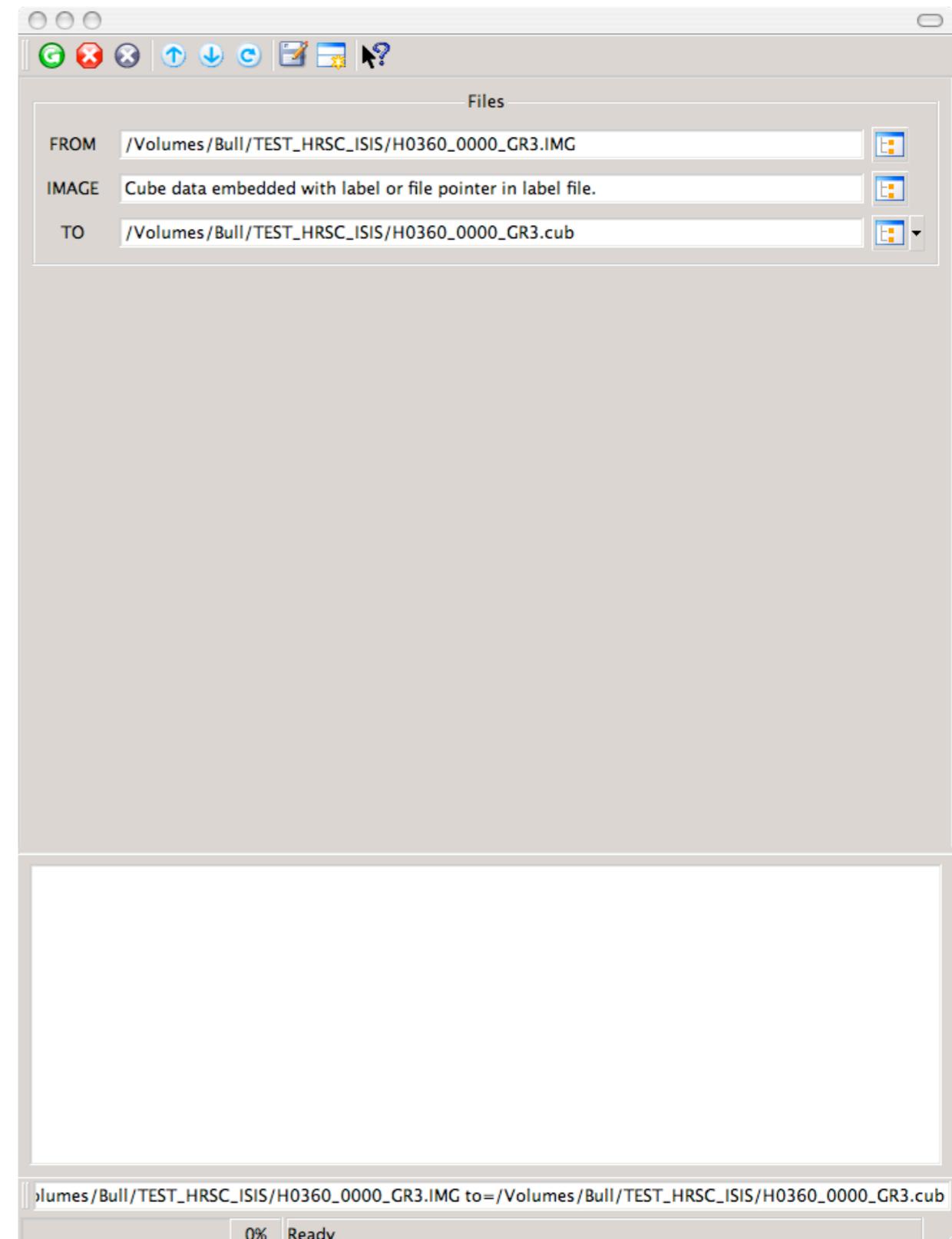
## PSA PDS Level3

“pds2isis”

[prompt:] pds2isis

### Disclaimer:

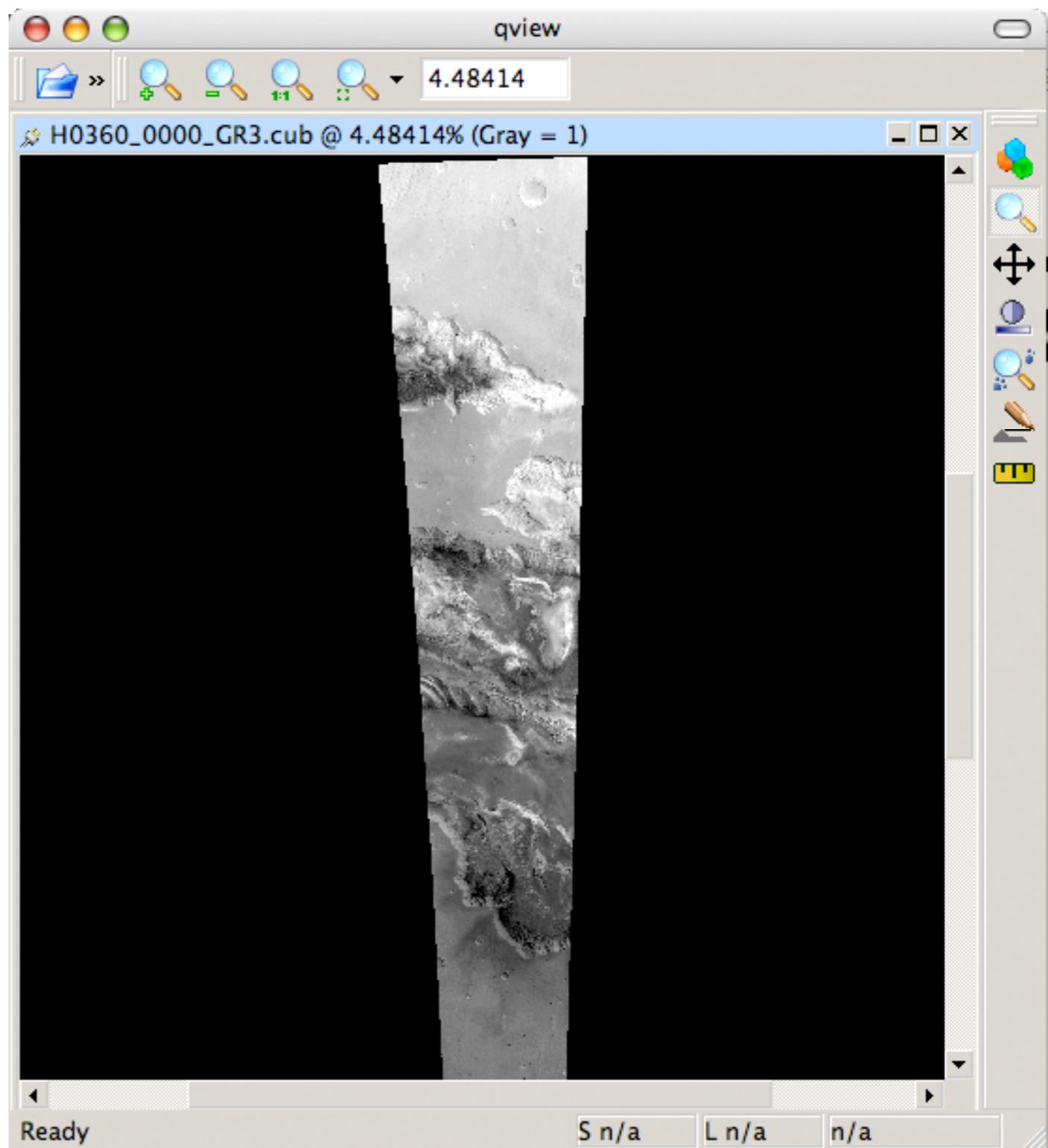
At this point HRSC data are not officially supported by ISIS3. All following information is provided “as is”.



# HRSC in ISIS3

## PSA PDS Level3

“qview”



# HRSC in ISIS3

## PSA PDS Level3

Currently (early June 2007) it looks like “pds2isis” imports some of the mapping keywords not correctly

imported header with pds2isis

“right” header

Group = Mapping	
ProjectionName	= Sinusoidal
CenterLongitude	= 285.0
TargetName	= Mars
EquatorialRadius	= 3396190.0 <meters>
PolarRadius	= 3396190.0 <meters>
LatitudeType	= Planetographic
LongitudeDirection	= PositiveWest
LongitudeDomain	= 180
MinimumLatitude	= -15.3784
MaximumLatitude	= 3.11736
MinimumLongitude	= 282.963
MaximumLongitude	= 287.18
UpperLeftCornerX	= -124862.5 <meters>
UpperLeftCornerY	= 185312.5 <meters>
PixelResolution	= 100.0 <meters/pixel>
Scale	= 592.74696512189 <pixels/degree>
TrueScaleLatitude	= 0.0
LineProjectionOffset	= 1853.625
SampleProjectionOffset	= 1249.125
End_Group	
End_Object	

Group = Mapping	
ProjectionName	= Sinusoidal
CenterLongitude	= 285.0
TargetName	= Mars
EquatorialRadius	= 3396190.0 <meters>
PolarRadius	= 3396190.0 <meters>
LatitudeType	= Planetographic
LongitudeDirection	= PositiveEast
LongitudeDomain	= 360
MinimumLatitude	= -15.3784
MaximumLatitude	= 3.11736
MinimumLongitude	= 282.963
MaximumLongitude	= 287.18
UpperLeftCornerX	= -124862.5 <meters>
UpperLeftCornerY	= 185312.5 <meters>
PixelResolution	= 100.0 <meters/pixel>
Scale	= 592.74696512189 <pixels/degree>
TrueScaleLatitude	= 0.0
LineProjectionOffset	= 1853.625
SampleProjectionOffset	= 1249.125
End_Group	
End_Object	

# HRSC in ISIS3

## PSA PDS Level3

“editlab”

a) remove “mapping”  
group from label

```
Group = Mapping
ProjectionName      = Sinusoidal
CenterLongitude     = 285.0
TargetName          = Mars
EquatorialRadius   = 3396190.0 <meters>
PolarRadius         = 3396190.0 <meters>
LatitudeType        = Planetographic
LongitudeDirection = PositiveWest
LongitudeDomain    = 180
MinimumLatitude     = -15.3784
MaximumLatitude    = 3.11736
MinimumLongitude    = 282.963
MaximumLongitude    = 287.18
UpperLeftCornerX   = -124862.5 <meters>
UpperLeftCornerY   = 185312.5 <meters>
PixelResolution     = 100.0 <meters/pixel>
Scale               = 592.74696512189 <pixels/degree>
TrueScaleLatitude   = 0.0
LineProjectionOffset = 1853.625
SampleProjectionOffset = 1249.125
End_Group
End_Object
```



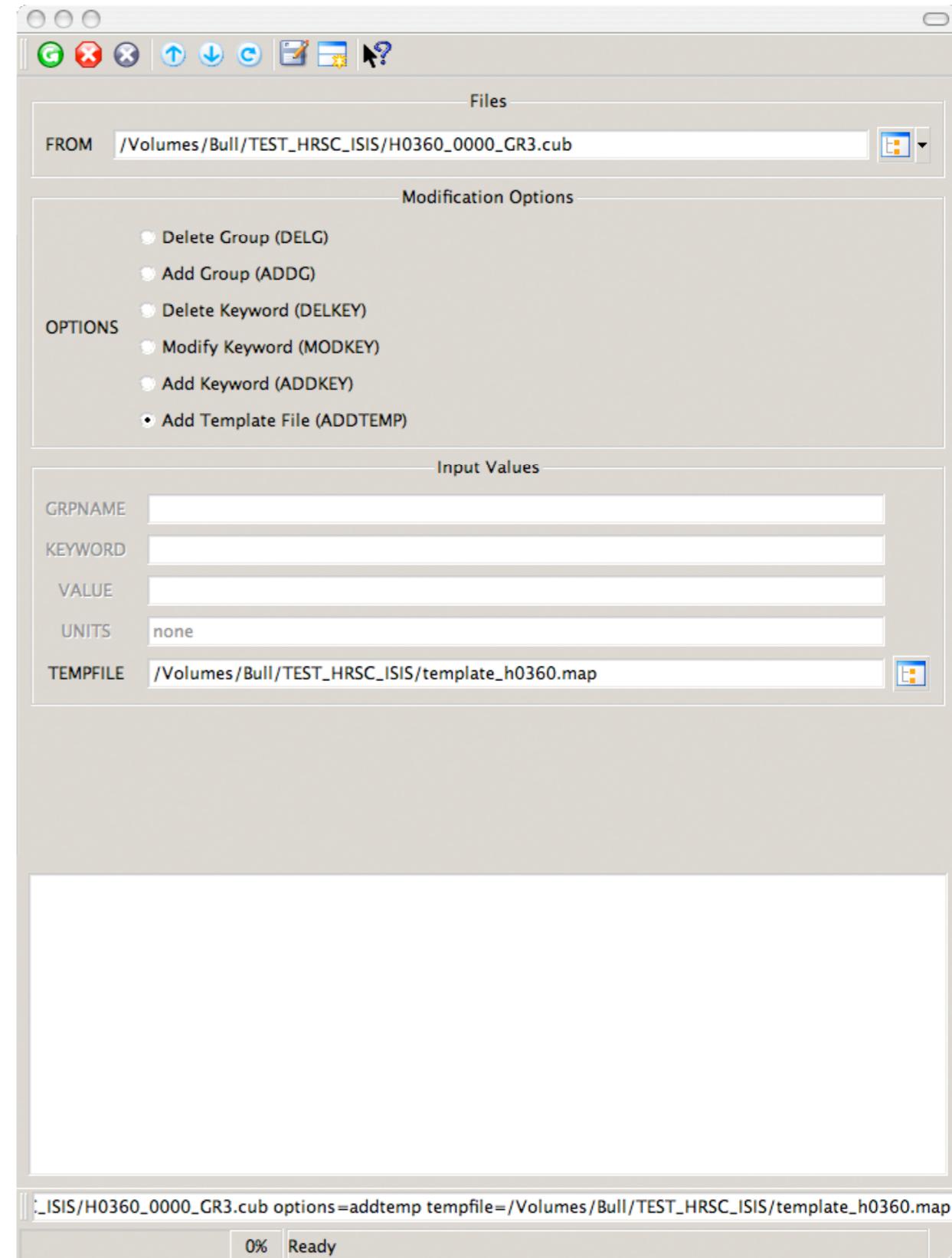
# HRSC in ISIS3

## VICAR Level3/3+

“editlab”

b) adding “mapping” group to label from corrected template

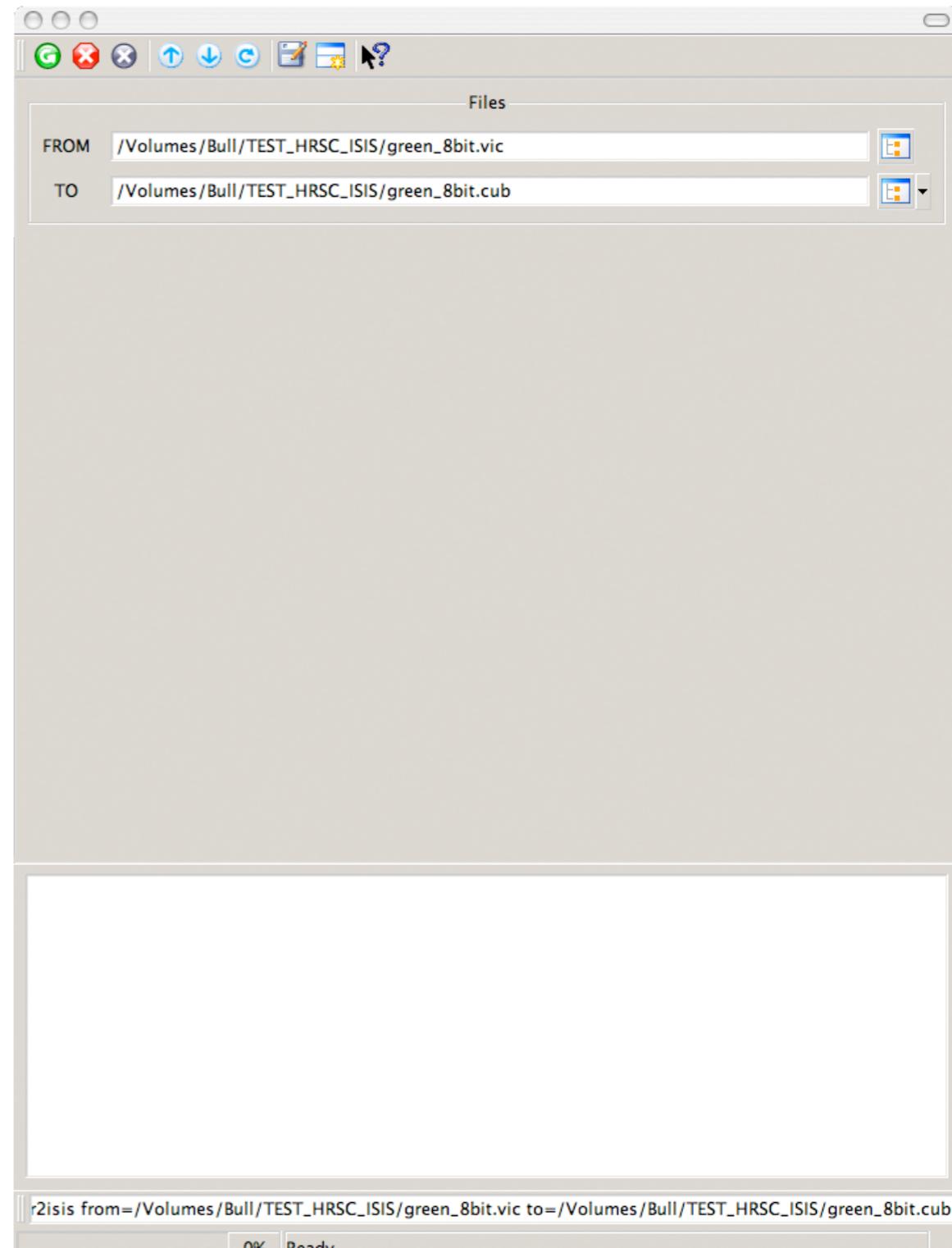
```
Group = Mapping
ProjectionName      = Sinusoidal
CenterLongitude     = 285.0
TargetName          = Mars
EquatorialRadius   = 3396190.0 <meters>
PolarRadius         = 3396190.0 <meters>
LatitudeType        = Planetographic
LongitudeDirection = PositiveEast
LongitudeDomain    = 360
MinimumLatitude     = -15.3784
MaximumLatitude    = 3.11736
MinimumLongitude    = 282.963
MaximumLongitude    = 287.18
UpperLeftCornerX   = -124862.5 <meters>
UpperLeftCornerY   = 185312.5 <meters>
PixelResolution     = 100.0 <meters/pixel>
Scale               = 592.74696512189 <pixels/degree>
TrueScaleLatitude   = 0.0
LineProjectionOffset = 1853.625
SampleProjectionOffset = 1249.125
End_Group
End_Object
```



# HRSC in ISIS3

## VICAR Level3/3+

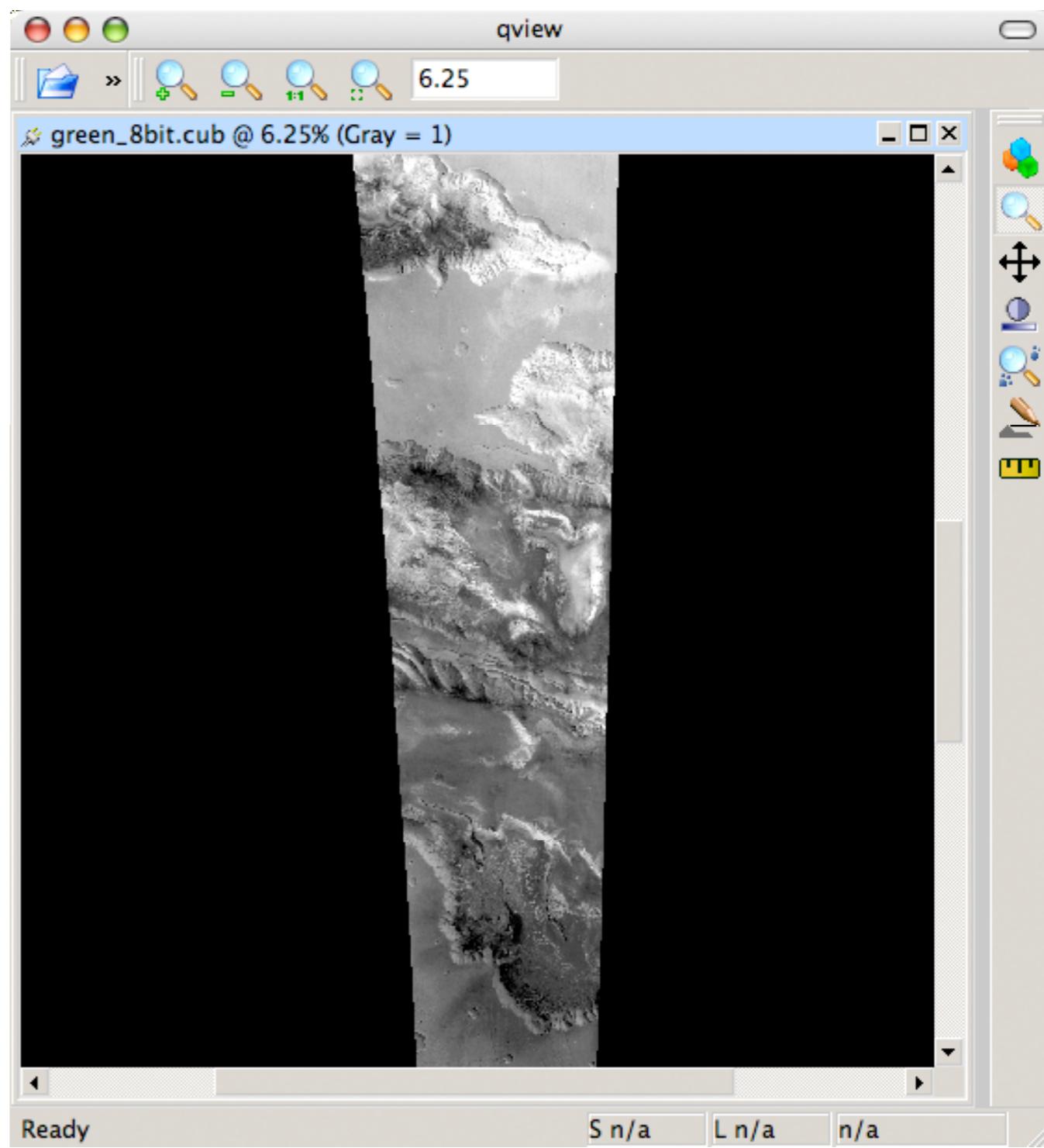
“vicar2isis”



# HRSC in ISIS3

## VICAR Level3/3+

“qview”



# HRSC in ISIS3

## VICAR Level3/3+

HRSC home-brewed  
Level3/+ in ISIS

**NOTE: map-related keywords are not  
automatically imported**

```
Object = IsisCube
Object = Core
StartByte    = 65537
Format       = Tile
TileSamples  = 128
TileLines    = 128

Group = Dimensions
Samples = 2497
Lines   = 10965
Bands   = 1
End_Group

Group = Pixels
Type      = UnsignedByte
ByteOrder = Lsb
Base     = 0.0
Multiplier = 1.0
End_Group
End_Object
End_Object

Object = Label
Bytes = 65536
End_Object

Object = History
Name    = IsisCube
StartByte = 28246017
Bytes   = 428
End_Object
End
```

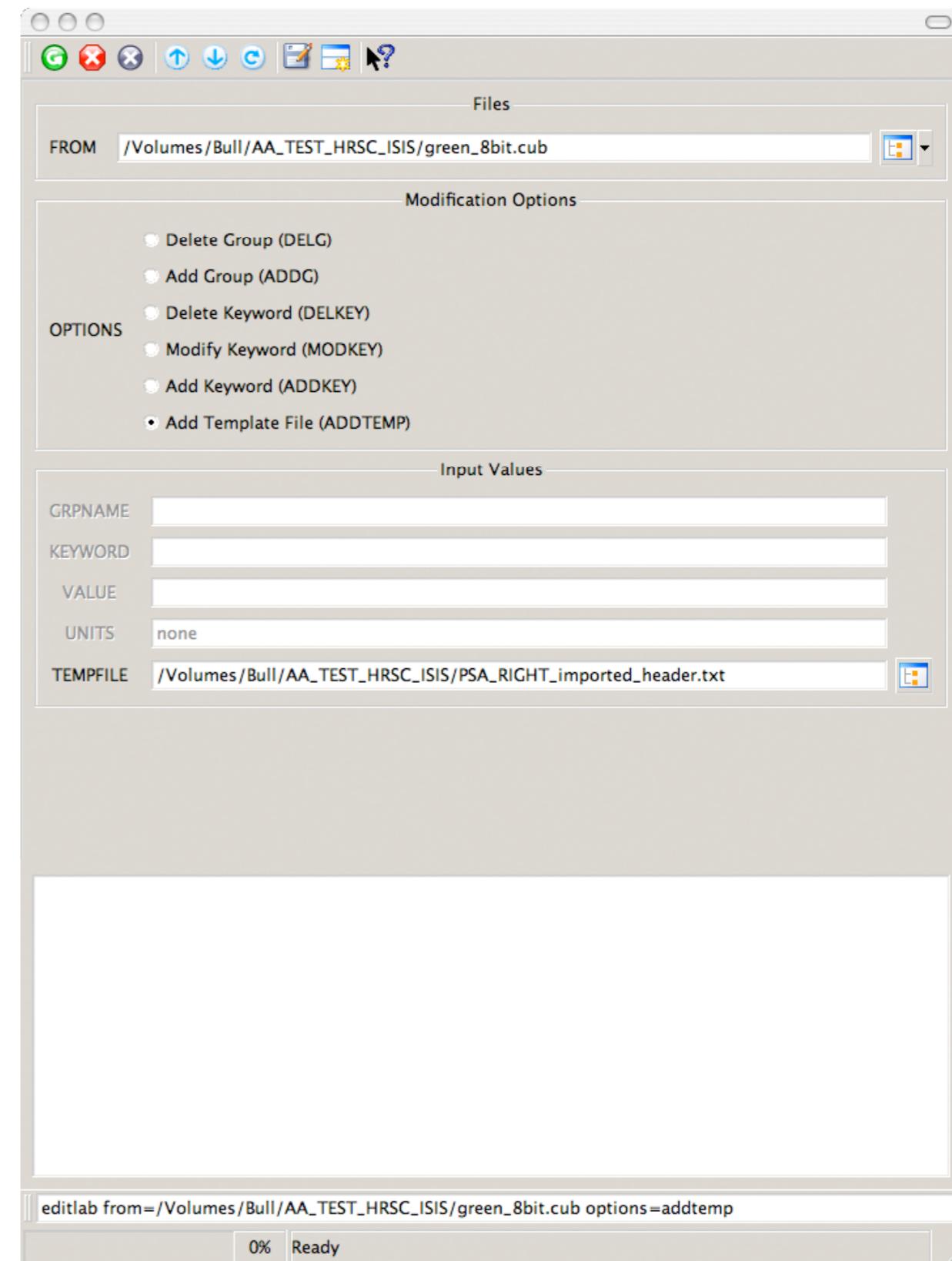
# HRSC in ISIS3

## VICAR Level3/3+

“editlab”

b) adding “mapping” group to label from corrected template

```
Group = Mapping
ProjectionName      = Sinusoidal
CenterLongitude     = 285.0
TargetName          = Mars
EquatorialRadius   = 3396190.0 <meters>
PolarRadius         = 3396190.0 <meters>
LatitudeType        = Planetographic
LongitudeDirection = PositiveEast
LongitudeDomain    = 360
MinimumLatitude     = -15.3784
MaximumLatitude    = 3.11736
MinimumLongitude    = 282.963
MaximumLongitude    = 287.18
UpperLeftCornerX   = -124862.5 <meters>
UpperLeftCornerY   = 185312.5 <meters>
PixelResolution    = 100.0 <meters/pixel>
Scale               = 592.74696512189 <pixels/degree>
TrueScaleLatitude   = 0.0
LineProjectionOffset = 1853.625
SampleProjectionOffset = 1249.125
End_Group
End_Object
```



# HRSC in ISIS3

## VICAR Level3/3+

```
Object = IsisCube
Object = Core
StartByte    = 65537
Format       = Tile
TileSamples  = 128
TileLines    = 128

Group = Dimensions
Samples = 2497
Lines   = 10965
Bands   = 1
End_Group

Group = Pixels
Type      = UnsignedByte
ByteOrder = Lsb
Base      = 0.0
Multiplier = 1.0
End_Group
End_Object
```

“Mapping” group added

```
Group = Mapping
ProjectionName      = Sinusoidal
CenterLongitude    = 285.0
TargetName          = Mars
EquatorialRadius   = 3396190.0 <meters>
PolarRadius         = 3396190.0 <meters>
LatitudeType        = Planetographic
LongitudeDirection = PositiveEast
LongitudeDomain    = 360
MinimumLatitude    = -15.3784
MaximumLatitude    = 3.11736
MinimumLongitude   = 282.963
MaximumLongitude   = 287.18
UpperLeftCornerX   = -124862.5 <meters>
UpperLeftCornerY   = 185312.5 <meters>
PixelResolution    = 100.0 <meters/pixel>
Scale               = 592.74696512189 <pixels/degree>
TrueScaleLatitude  = 0.0
LineProjectionOffset = 1853.625
SampleProjectionOffset = 1249.125
End_Group
End_Object
```

```
Object = Label
Bytes = 65536
End_Object
```

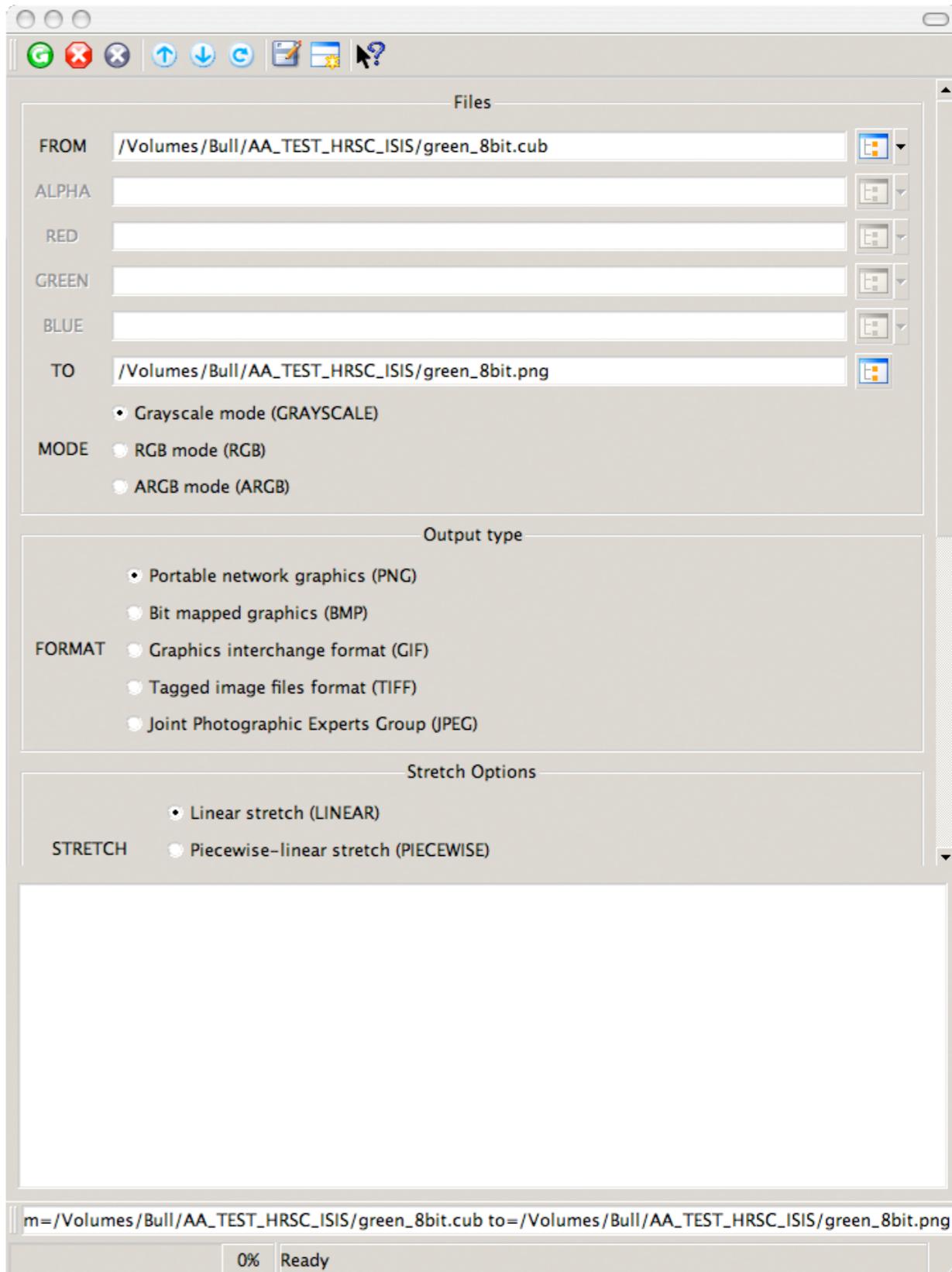
```
Object = History
Name      = IsisCube
StartByte = 28246017
Bytes     = 428
End_Object
End
```

# HRSC in ISIS3

## VICAR Level3/3+

“isis2std”

Exports to GIS-friendly  
formats



# HRSC, ISIS, etc.

- With a bit of time, you should be able to integrate HRSC single bands, anaglyphs, RGB & pan-sharpened RGB with other datasets (e.g. MOC, THEMIS VIS, THEMIS IR) within your GIS software/environment.
- Once you have your coregistered (same number of lines and columns) HRSC bands and you're adventurous enough, you can try mosaicking or other fancy things with ISIS

Good luck!