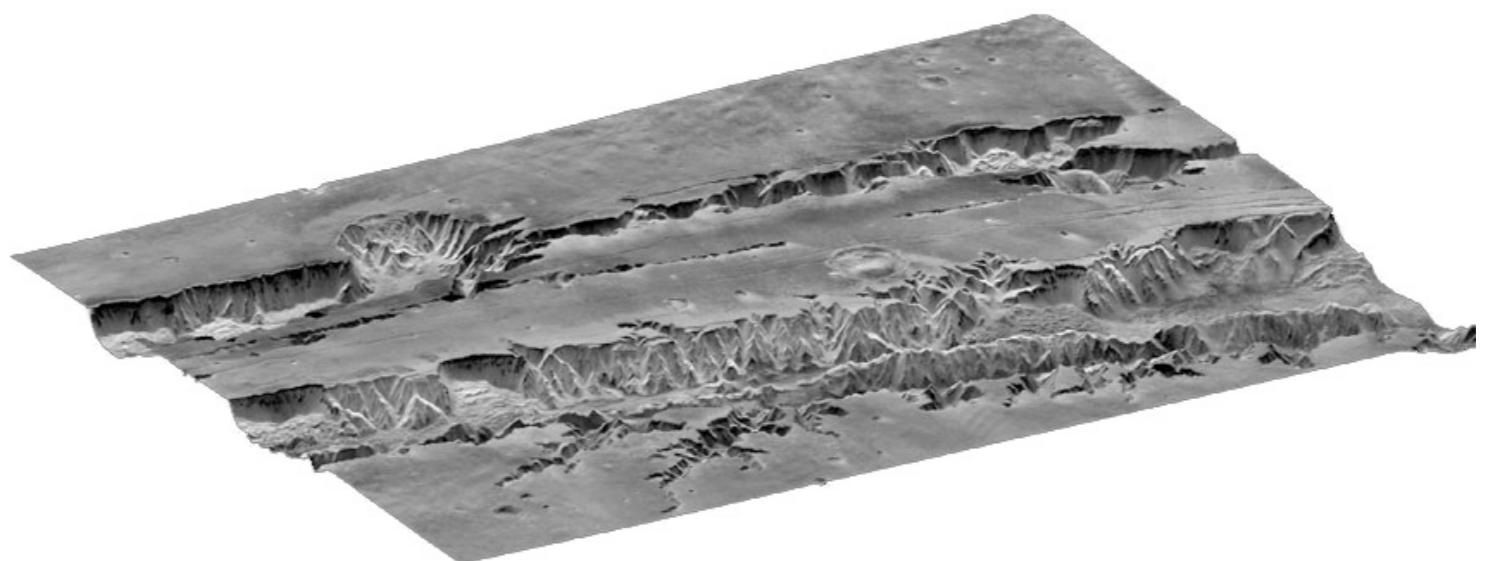


# HRSC Introduction

Angelo Pio Rossi

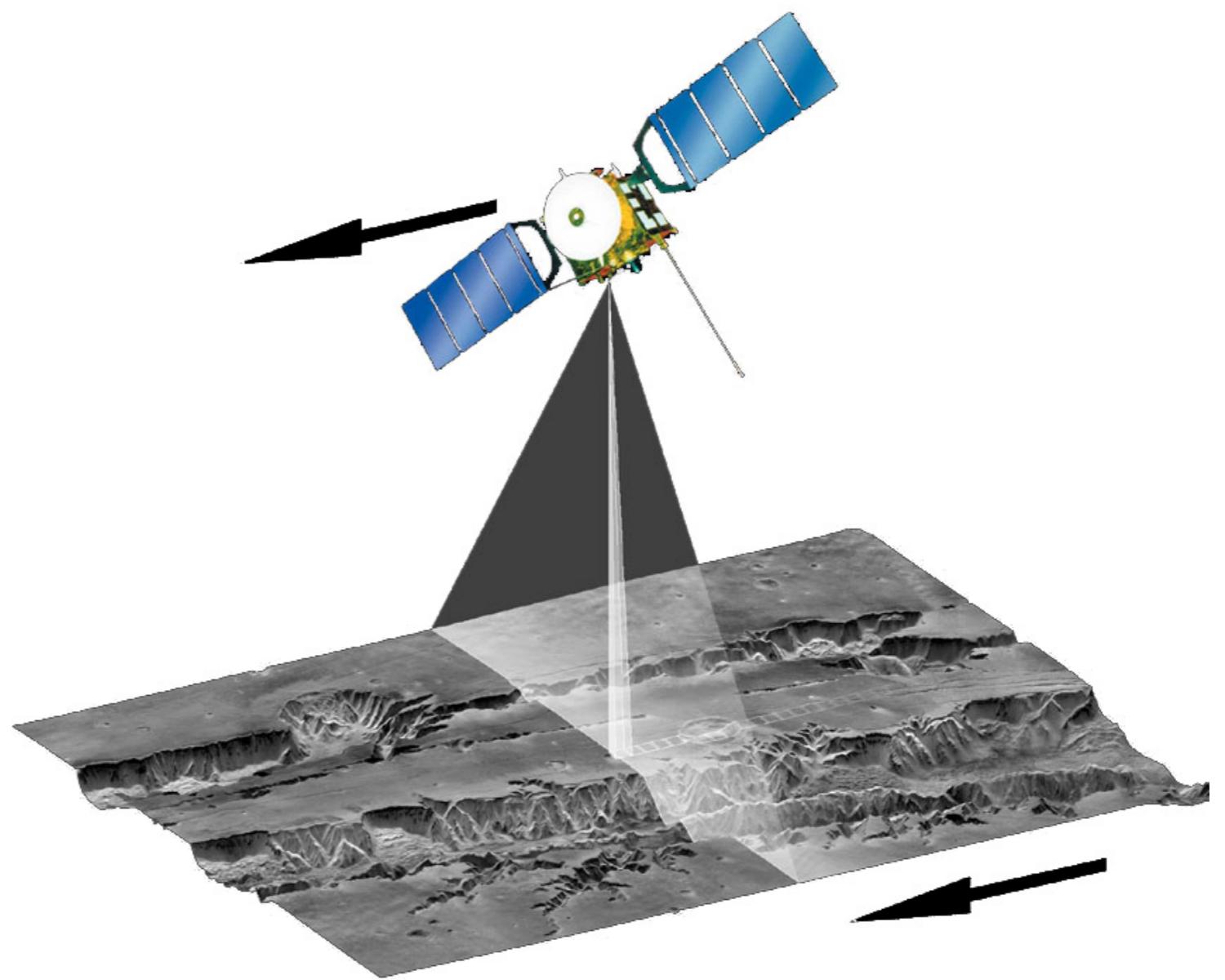
# HRSC stereo

HRSC stereo  
imaging principle



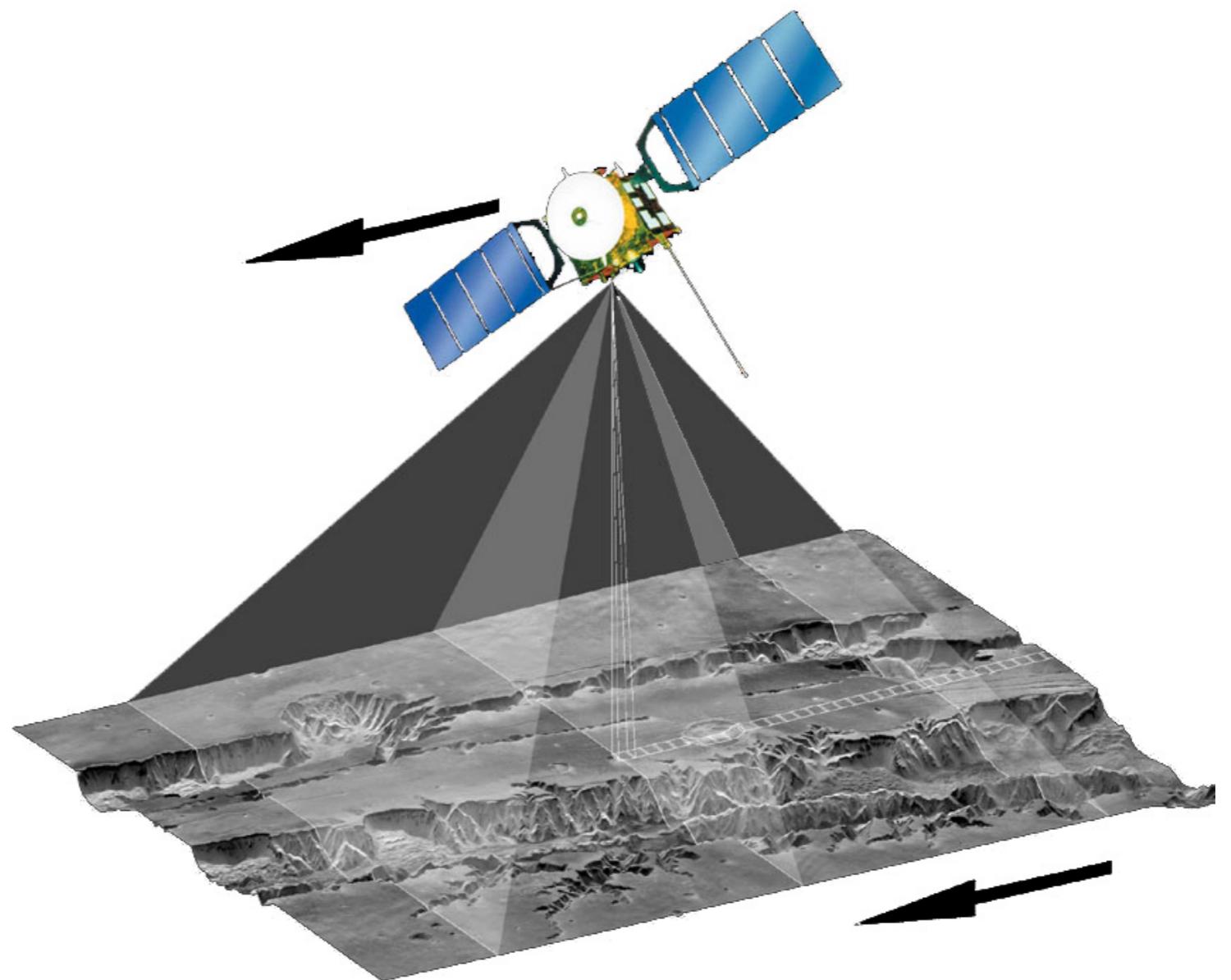
# HRSC stereo

HRSC stereo  
imaging principle



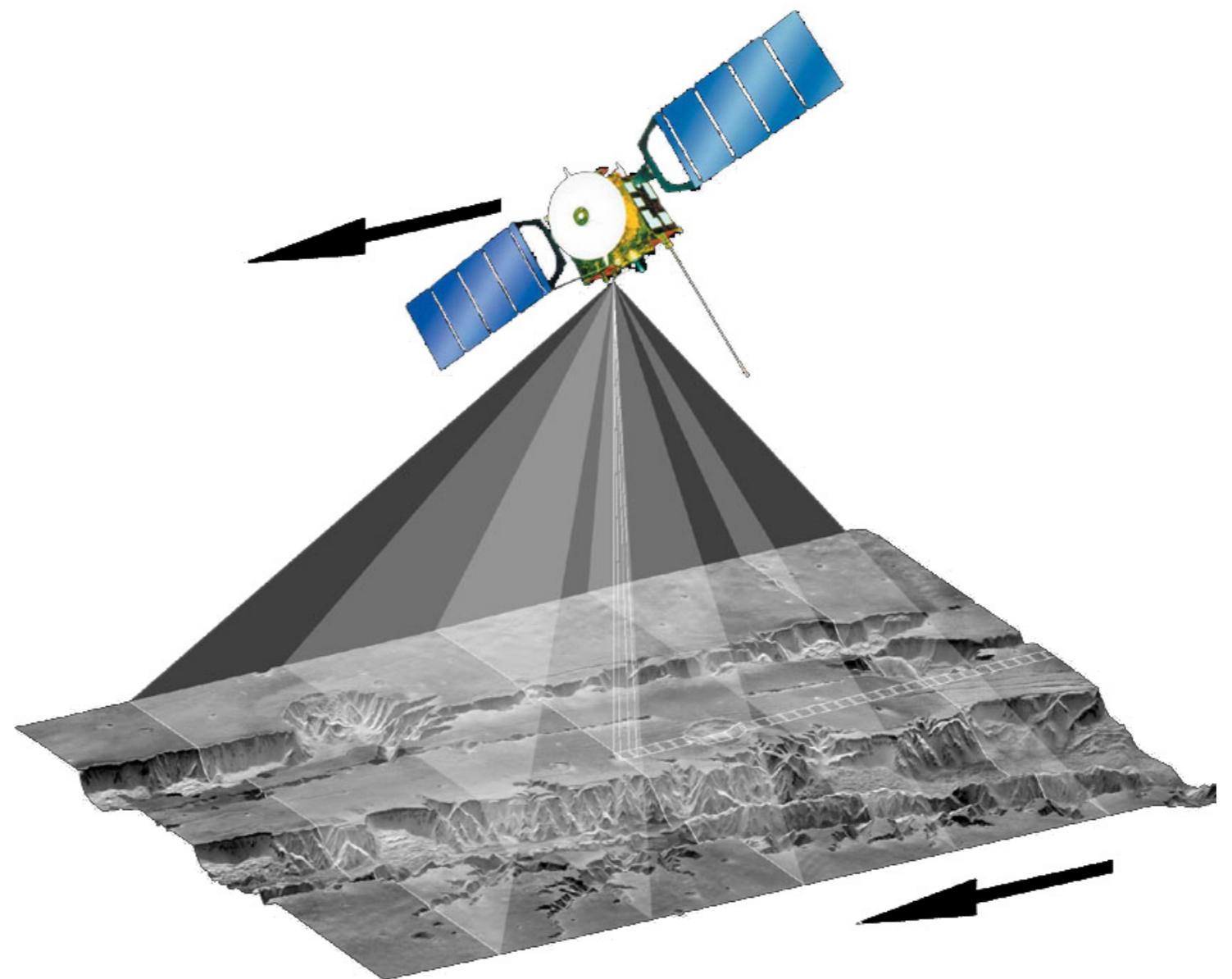
# HRSC stereo

HRSC stereo  
imaging principle



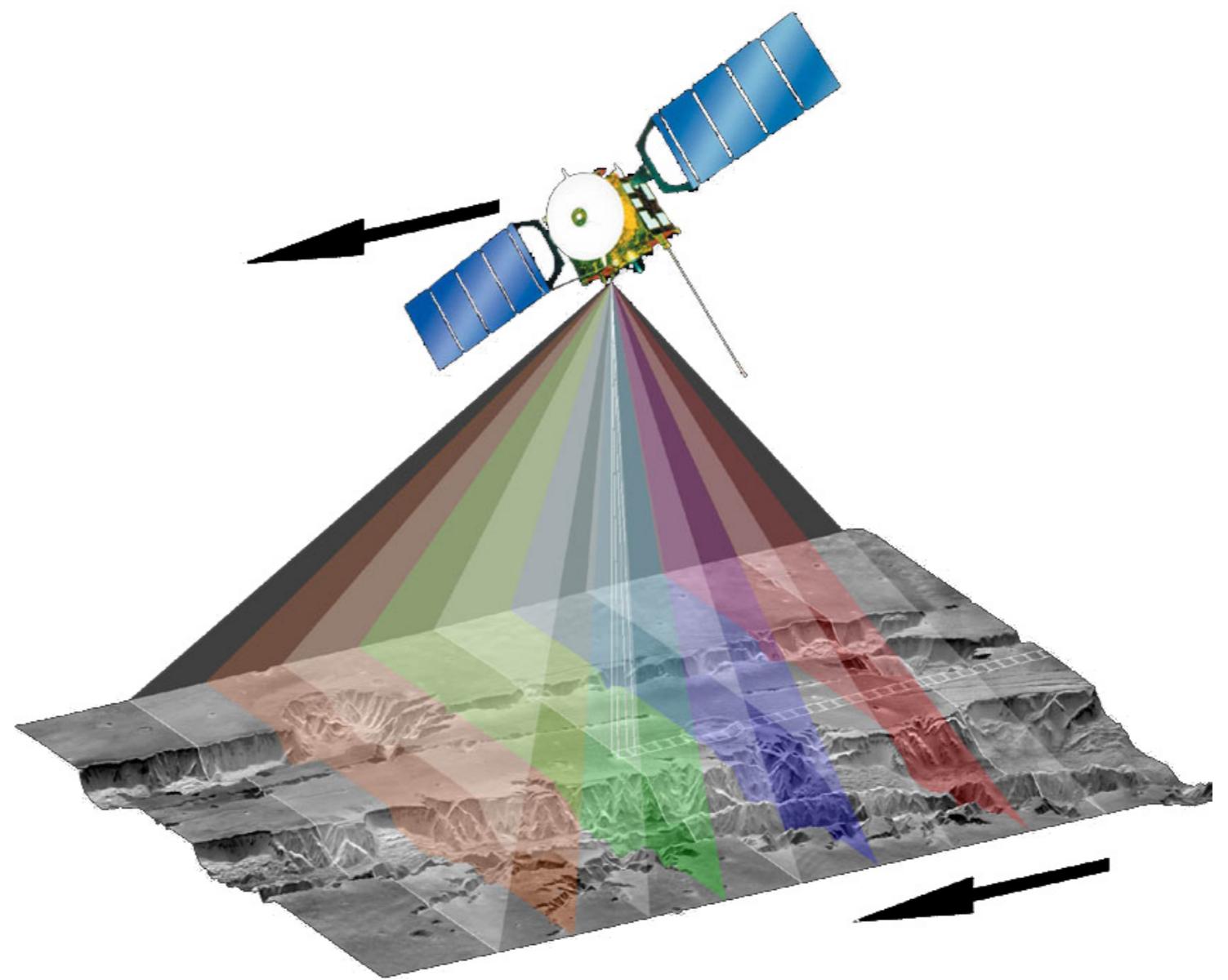
# HRSC stereo

HRSC stereo  
imaging principle



# HRSC stereo

HRSC stereo  
imaging principle



# HRSC data products

- Level-2: Radiometrically Calibrated DataInput for Photogrammetric Processing
- Level-3: Geometrically Corrected and Map ProjectedStandard Products for Geology
- Based on available SPICE kernels (may be predicted SPK, CK)

# HRSC data products

- Radiance = RADIANCE\_OFFSET +DN \* RADIANCE\_SCALING\_FACTOR (Unit is W\*m\*\*-2\*sr\*\*-1)
- Reflectance = DN \* REFLECTANCE\_SCALING\_FACTOR

# Data type

- The data will be signed 16-bit data either from data transmitted as 14-bit data (SRC only) or 8-bit data.
- The format of the data will be in raster form.
- All dark, dummy, isolation, and affected pixel are removed from the image.

# Level2 data

Error pixel are marked with the following negative values:

- 1 blemish pixel one pixel for SRC for one blemish  
one whole column for HRSC for one blemish

- 2 bad pixel (telemetry or decompression problems)

typical size: 8 lines x 512 pixels

- 8 saturated pixel

Bad pixels affect other pixels during compression (8x8) !

# File naming conventions

The following structure of filenames will be used:

**Hoooo\_mmmp\_DDI.IMG**

- camera id
- orbit number
- image number in one orbit
- detector id
- (can be **nd, s1, s2, p1, p2, re, ir, gr, bl, l0, l1, sr**)
- level (0,1,2,3)
- version
- example:

**H**  
**oooo**  
**mmmp**  
**dd**  
**l**  
**vv**  
**H1234\_0023\_ND2.IMG**

(small letters at PDS)

# Level3 data

MEX-M-HRSC-5-REFDR-MAPPROJECTED-V2.0

- Sinusoidal projection for  $|\text{center\_latitude}| < 85^\circ$ ,  
radius = 3396.19
- Stereographic projection  $|\text{center\_latitude}| > 85^\circ$ ,  
radius = 3376.2

# HRSC - name examples

H0000\_0000\_ND2.IMG

ND = nadir

H0000\_0000\_S12.IMG

S1 = stereo1

H0000\_0000\_S22.IMG

S2 = stereo2

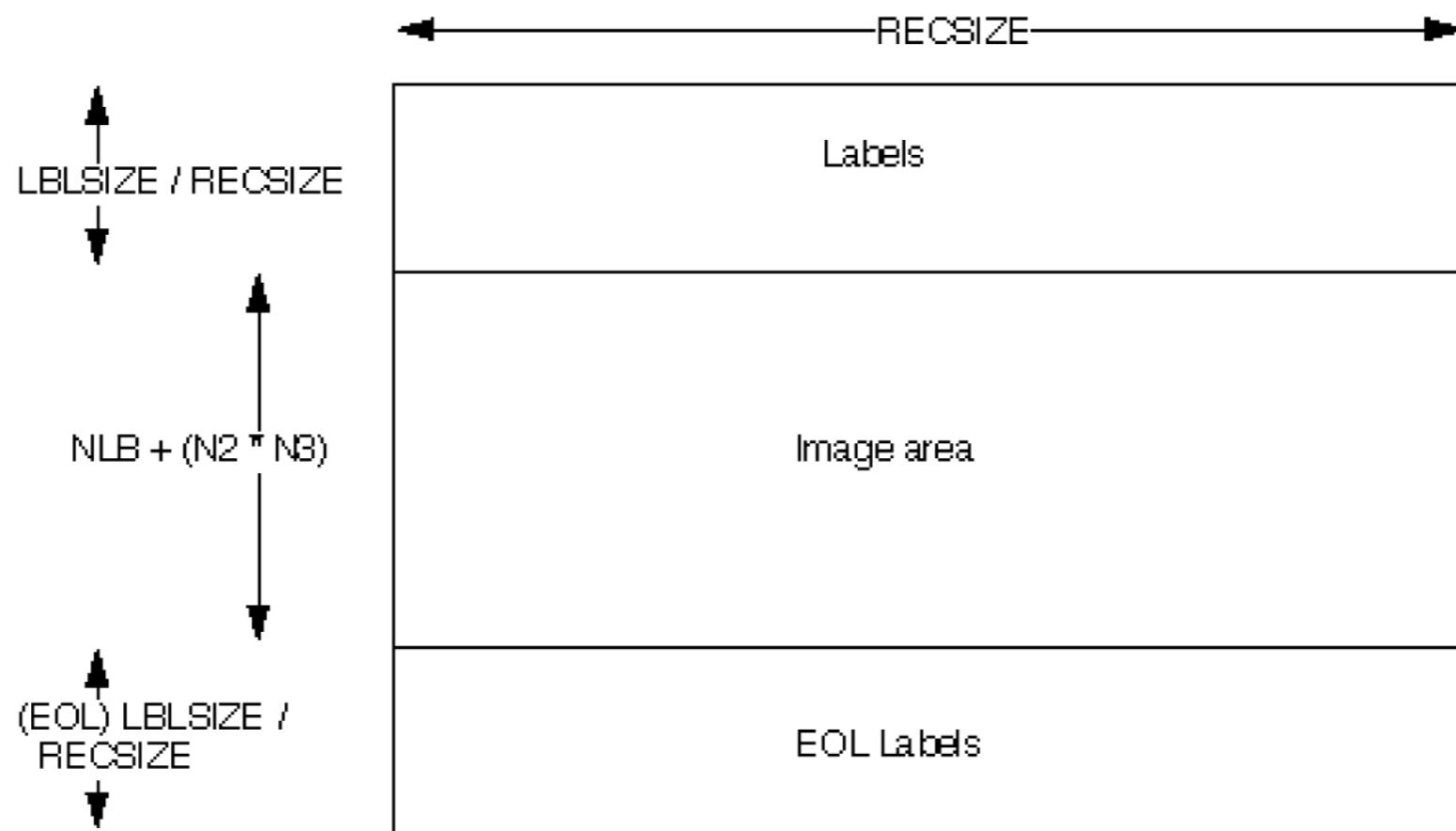


processing level  
(Level2)

# miniVICAR - history

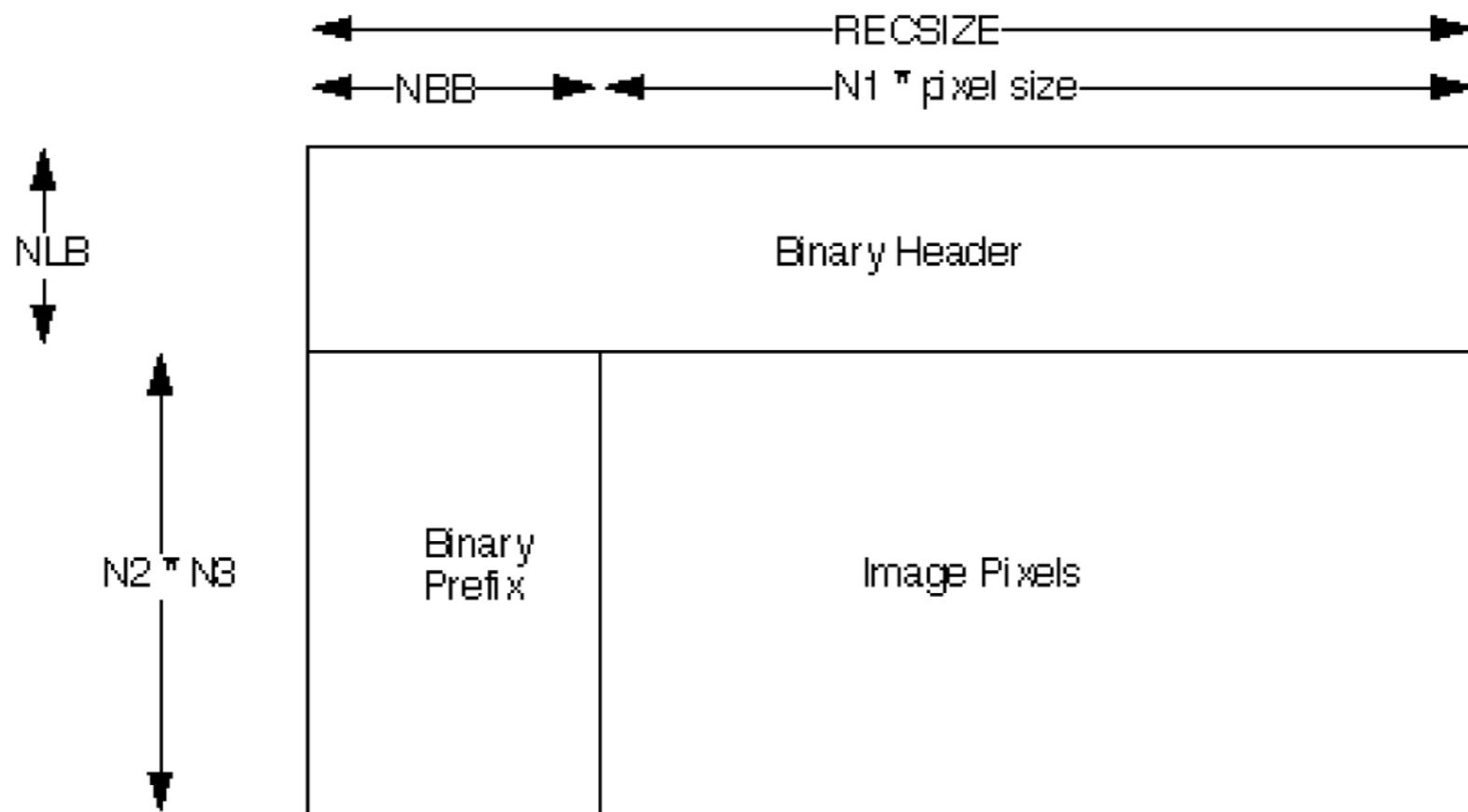
- Implemented in 1966 at the Jet Propulsion Laboratory to process image data produced by the planetary exploration program
- Originally designed for operation with the IBM 360/44 Programming System (44PS)
- Ported to IBMOS/360, VAX-VMS, and Alpha-VMS
- Now running under Sun-Solaris and x86-Linux

# miniVICAR



- NLB      Number of Lines of binary header
- N2      Number of Images Lines (for BSQ)
- N3      Number of Bands (for BSQ)

# miniVICAR



- NLB** Number of Lines of Binary header
- NBB** Number of Bytes of Binary prefix
- N1** Number of Image Samples (for BSQ)
- N2** Number of Images Lines (for BSQ)
- N3** Number of Bands (for BSQ)

# Data types

- BYTE: unsigned single byte, 0 / 255
- HALF: signed two byte integer, -32768 / 32767
- FULL: signed four byte integer, -2147483648 / 2147483647
- REAL: four byte real
- DOUB: eight byte real
- COMP: ever used ?

# miniVICAR programs

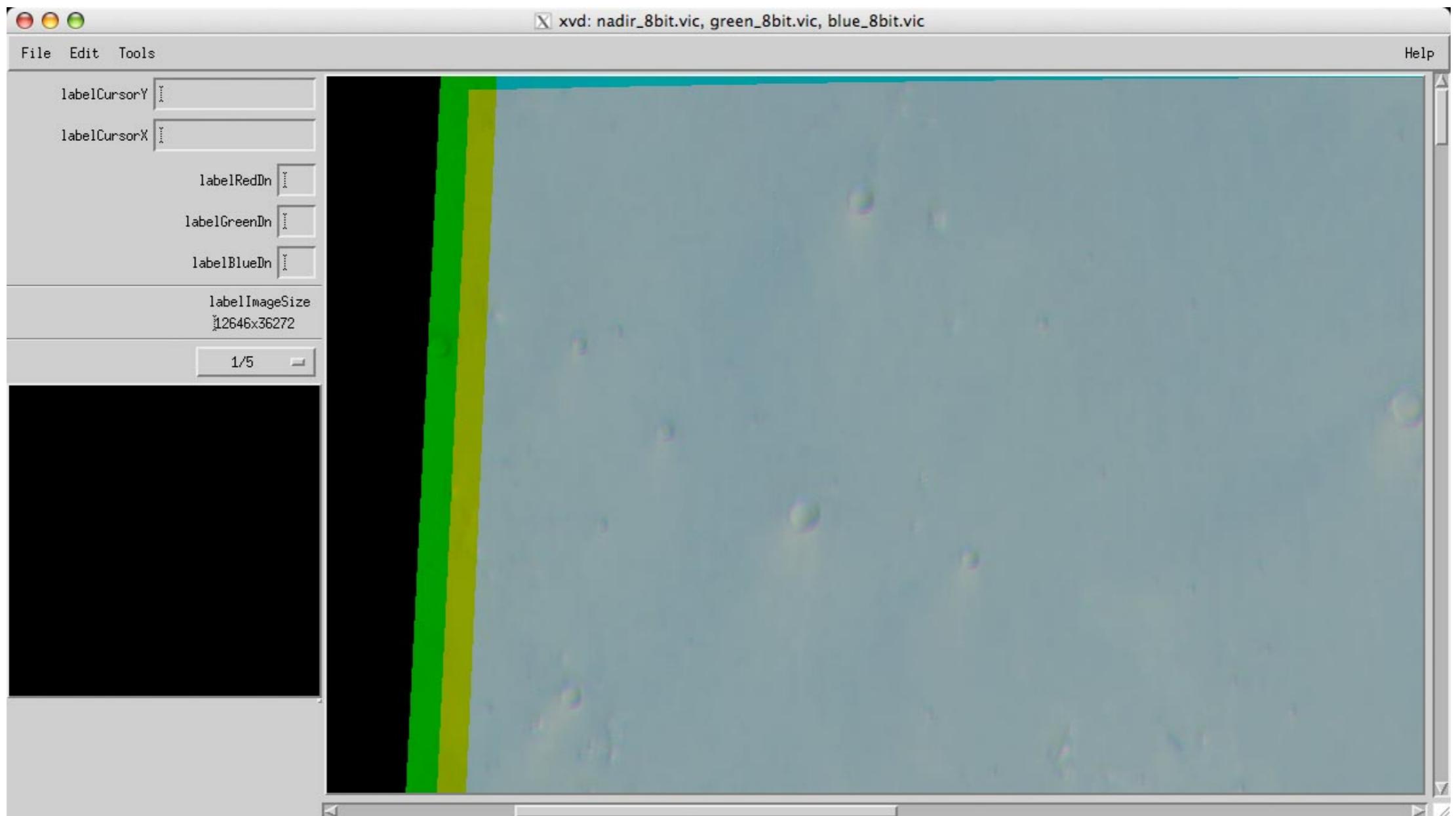
- Every program consists of an executable and a PDF(program definition file),
- Must be in the same directory
- PDF is an ASCII file and contains detailed help for the program
- Software distributed as source code
- Executables available from PSA

[ftp://gorilla.estec.esa.int/pub/projects/workshop/04\\_MEX\\_DW\\_june\\_2007/software\\_data/minivicar](ftp://gorilla.estec.esa.int/pub/projects/workshop/04_MEX_DW_june_2007/software_data/minivicar)

# General programs

- xvd: PDS and VICAR display program
- Label: prints and modifies the label  
label -list test.dat
- label -remove test.dat test.raw  
label -create test.raw test2.dat  
nl=100 ns=50 -ha
- dlrvic2png: converts VICAR to PNG(Problem:  
VICAR signed 16-bit, PNG unsigned 16-bit)

# xvd



# hrfill

Syntax:

**\$HWLIB/hrfill inp=... out=... [optionals]**

- This program changes the DN value of all pixels which were flagged as bad during the calibration process
- hrfill tries to fill the pixels with useful values:=  
**Maximum\_of\_valid\_pixels+1**
- For the saturated pixels= Median of the surrounding valid pixels otherwise
- Output will be written only if something has to be filled !

# dlrto8

Syntax:

`$HWLIB/dlrto8 inp=... out=... [optionals]`

- dlr12to8 uses image histograms of signed 16-bit integer images to derive look-up tables for the conversion into 8-bit images using a linear transformation.
- The lower and upper borders of the input data range can be defined using
  - a) explicit values (DNMIN, DNMAX)
  - b) percentages of image pixels (LOWER, UPPER).
- DNs lower than the LOWER or higher than the UPPER percentages of all pixels are ignored in defining the transformation function.

# hrortho

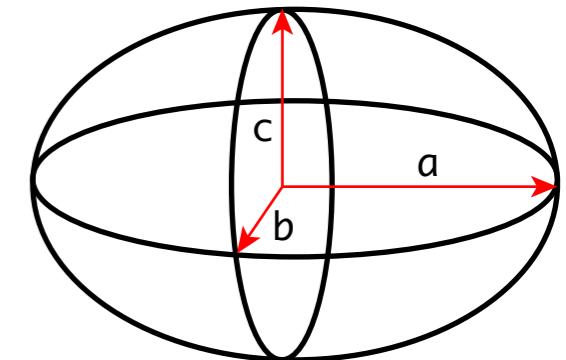
Syntax:

`$HWLIB/hrortho inp=... ori=spice dtm=... out=... [optionals]`

<code>dtm=...</code>	dtm-file or height above datum in meter
<code>inp=...</code>	Input image used if
<code>out=...</code>	Output image generated
<code>ori=spice</code>	(spice KERNELS used)
<code>fitto=...</code>	File to which OUT should fit.
<code>sL_inp=...</code>	starting lines of input Level2 image
<code>nl_inp=...</code>	no. lines starting from nl_inp to be processed

“hrortho” produced map projected HRSC images

# hrortho



mp\_type=... type of output projection  
outmax=... size limit for output image [in MegaByte]  
a\_axis=... value of the a-axis of a solar system body  
b\_axis=... value of the b-axis of a solar system body  
c\_axis=... value of the c-axis of a solar system body  
( DEFAULT a\_axis=b\_axis=3396.19 c\_axis=3376.2 )  
mp\_scale=... measured in kilometers per pixel  
cen\_lat=... reference latitude for certain map projections  
cen\_lon=... reference longitude for certain map projections

For other parameters, have a look at:

[\\$V2T0P/hw/lib/x86-linux/hrortho.pdf](#)

(it's ASCII file, NOT an Adobe .pdf)

# frameortho

Syntax:

`$HWLIB/frameortho inp=... out=... [optionals]`

- map projection program for frame sensor data
- input are image, SPICE kernels and geometriccalibration files
- user can specify:
  - map resolution
  - map projection type
  - center latitude and center longitude
  - many other parameters

# SPICE kernels to use

- IK, FK, PCK, SCLK
  - latest version
- SPK and CK :
  - Check START\_TIME in image label
  - select corresponding Kernel

# Also in miniVICAR

- vicar
  - subset of VICAR from MIPL/JPL
    - DLR programs to process HRSC data
- geocal:
  - Geometric calibration files for line sensors
- data:
  - global Mars-DTM derived from MOLA data to be used as reference body in \*ortho (default is the IAU ellipsoid)

# Environmental Variables

```
#!/bin/tcsh

# MINIVICAR VARIABLES
setenv V2TOP /<PATH>/minivicar/vicar
source $V2TOP/vicset1.csh
source $V2TOP/vicset2.csh
setenv M94GEOCAL $V2TOP/./GEOCAL
setenv PATH $V2TOP:{$PATH}

# VARIABLES FOR KERNELS AND DATA
setenv LEAPSECONDS $V2TOP/./kernels/NAIF0008.TLS
setenv CONSTANTS $V2TOP/./kernels/PCK00008.TPC
setenv SUNKER $V2TOP/./kernels/DE405S.BSP
setenv HWSPICE_TF $V2TOP/./kernels/MEX_V08.TF
setenv HWSPICE_TI $V2TOP/./kernels/MEX_HRSC_V03.TI
setenv HWSPICE_TSC $V2TOP/./kernels/MEX_070321_STEP.TSC
setenv HWSPICE_BC ./ATNM_P030602191822_00135.BC
setenv HWSPICE_BSP ./ORMM__050301000000_00117.BSP
```